Solution of Algebraic Equations by Using Autonomous Computational Methods

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AMS Fall Central Sectional Meeting September 12-13, 2020

Outline





2 Mathematics



3 Engineering



Generalizations





Summary

- Mathematics Engineering
- Conclusions

- Part 1: Formal Methods
 - Education
 - Mathematics
 - Engineering
 - Generalization
- Part 2: Autonomous Computational Methods

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Online Learning

Education

Mathematics Engineering Generalization Conclusions



Early Examples of Distance Learning

Education

- Mathematics Engineering
- c . . .



Online Learning

Education

- Mathematics
- Engineering
- Generalizations
- Conclusions

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Last Name:	Andrew
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Files (notes, syllabus etc.)

Online Learning (List of Students, Data Storage)

Education

- Mathematics Engineering
- Generalizations
- Conclusions

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Online Learning (Information about the Student)

Education

Mathematic

Engineering

Generalizations

Conclusions

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Online Learning (Online Homework)

Education

- Mathematics Engineering
- Conclusions

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Online Learning (Online Homework)

Education

- Mathematics Engineering Generalizatior
- Conclusions

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Online Learning (Online Visualization)

Education

Mathematic

Engineering

Generalizations

Conclusions





Figure: Solution of the heat transfer equation

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Online Learning (Online Visualization)



Figure: Solution of the heat transfer equation

$$\lambda \left(\frac{\partial^2 T}{\partial x^2} + \frac{\partial^2 T}{\partial y^2} \right) + \dot{q} = \rho c_p \frac{\partial T}{\partial t}$$

Online Learning (Online Visualization)

Education

Mathematic Engineering

Generalizations

Conclusions



$$\begin{cases} -c\left(\frac{\partial^{4}u}{\partial x^{4}} + \frac{\partial^{4}u}{\partial y^{4}}\right) + q = \frac{\partial^{2}u}{\partial t^{2}}\\ u(x, y) = 0, \quad \text{for} \quad (x, y) \in \partial\Omega\\ \frac{\partial^{2}u}{\partial x^{2}}(0, y, t) = \frac{\partial^{2}u}{\partial x^{2}}(L, y, t) = 0\\ \frac{\partial^{2}u}{\partial y^{2}}(x, 0, t) = \frac{\partial^{2}u}{\partial y^{2}}(x, L, t) = 0\\ u(x, y, 0) = u^{*}(x, y) \end{cases}$$

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Figure: Vibration of plates

Sample Problem

Education

- Mathematics
- Engineering
- Generalizations
- Conclusions

- Find area of the parallelogram for $\bar{a} = [1, 2, 3]$, $\bar{b} = [3, 2, 1]$. Answer: $A = |\bar{a} \times \bar{b}| = 4\sqrt{6}$.
- How to input $4\sqrt{6}$ into the system in order to provide the answer?
- It is possible to use text description of the expression. For example:

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- 4 * *sqrt*(6)
- 4 * *Sqrt*[6]
- 4*sqrt*(6)
- 4sqrt6
- 4 · sq6
- etc.

Parse Tree

Education

Mathematics

Engineering

Generalization

Conclusions

Parse tree



XML Parse Tree

Education

Mathematics

Engineering

Generalizations

Conclusions

Parse tree

statement: ifStatement grammar whileStatement letStatement
statements: statement*
ifStatement: 'if' '('expression')' '{'statements'}'
whileStatement: 'while' '('expression ')' '{'statements '}'
letStatement: 'let' varName '=' expression ';'
expression: term (op term)?
term: varName constant
varName: a string not beg. with a digit
constant: a decimal number
op: '+' '-' '=' '>' '<'

Same parse tree, in XML <whileStatement> parser output <keyword> while </keyword> <symbol> (</symbol> <expression> (term) <identifier> count </identifier> </term> <symbol> < </symbol> <term> <intConstant> 100 </intConstant> </term> </expression> <symbol>) </symbol> <symbol> { </symbol> <statements> <letStatement> <keyword> let </keyword> <identifier> count </identifier> <symbol> = </symbol> <expression> <term> <identifier> count </identifier> </term> <symbol> + </symbol> <term> <intConstant> 1 </intConstant> </term> </expression> <symbol> ; </symbol> </letStatement> </statements> <symbol> } </symbol> </whileStatement>

Grammar

Education

Mathematic

Engineering

Generalizations

Conclusions

Lexical elements:	The Jack language includes five types of terminal elements (tekens):				
keyword:	'class' 'constructor' 'function' 'method' 'field' 'static' 'var' 'int' 'char' 'boolean' 'void' 'true' 'false' 'null' 'this' 'let' 'do' 'if' 'else' 'while' 'return'				
symbol:	$\mathcal{L}(A) = \mathcal{L}(A) = \mathcal{L}$				
integerConstant:	A decimal number in the range 0 32767.				
StringConstant	"" A sequence of Unicode characters not including double quote or newline ""				
identifier:	A sequence of letters, digits, and underscore ('_') not starting with a digit.				
Program structure:	A Jack program is a collection of classes, each appearing in a separate file. The compilation unit is a class. A class is a sequence of tokens structured according to the following context free syntax:				
class:	'class'className '{'classVarDec* subroutineDec*'}'				
classVarDec:	('static' 'field') type varName (', 'varName)* ';'				
type:	'int' 'char' 'boolean' className				
subroutineDec:	('constructor' 'function' 'method') ('void' type) subroutineName '('parameterList')' subroutineBody				
parameterList:	((type varName) (', 'type varName)*)?				
subcoutineBody:	'{' varDec* statements '}'				
varDec:	'waz' type varName (', ' varName)* '; '				
className:	identifier				
subroutineName:	identifier				
varName:	identifier				
Statements:					
statements:	statement*				
statement:	letStatement ifStatement whileStatement doStatement returnStatement				
letStatement:	'let' vanName ('[' expression ']')? '=' expression '1'				
ifStatement:	'11'' (' expression ') ''{' statements '}' ('else'' {' statements '}')?				
whileStatement:	'while''('expression')''{'statements')'				
doStatement:	'do' subroutineCall ')'				
ReturnStatement	'return' expression?';'				
Expressions:					
expression:	term (op term)*				
term:	integerConstant stringConstant keywordConstant varName varName '['expression ']' subroutineCall '('expression ')' unaryOp term				
subroutineCall:	subroutineName '('expressionList')' (className varName)', 'subroutineName '('expressionList')'				
expressionList:	(expression (°, ' expression)*)?				
op:	$ A_{i} _{\mathcal{A}} _{\mathcal{A}}$				
unaryOp:	w I w				
KeywordConstant:	'true' 'false' 'null' 'this'				

Infix notation, Prefix notation, Postfix notation

Education

Mathematics Engineering

Generalizations

Conclusions

Different notation for arithmetic expressions.

- Infix notation (5+6)x7
- Prefix notation x + 567
- Postfix notation 756 + x

Typical evaluation process of arithmetic expressions.

- InfixToPrefix((5+6)x7)=x+567
- EvaluatePrefix(x + 567) = 77

Expression Tree

Education

- Mathematic
- с. н. н.
- Conclusions



((1+2)*(3-4))

How to Evaluate Mathematical Expression Given as a String?

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Education

Mathematics Engineering Generalization

Conclusions

Example

- Expression: sqrt(2)*6
- Value: $\sqrt{2} \cdot 6$

Example

- Expression: sqrt2*6
- Value: $\sqrt{2} \cdot 6$

Example

- Expression: Sqrt[2]6
- Value: $\sqrt{2} \cdot 6$

Example

- Expression: SQRT[2]6
- Value: $\sqrt{2} \cdot 6$

Automated Generation of Homework Assignments

Education

- Mathematics Engineering
- Generalization
- Conclusions

Differentiation, vector algebra, numerical integration, etc.

- Automatically generated list of formulas with given level of difficulty.
- Latex representation of given formula.
- Evaluation of formulas and generation of tests.
- Appropriate HTML code which implements all elements.
- Upload to server and add integrate with the grading system for appropriate group of students, due dates.

Theoretical Aspects of Online Learning

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onclusions	Published by print	t and online quarterly, En	ACADEMIC			
	ISSN: 1752-8909 ISSN: 1752-8917	ISSN: 1752-8909 (print) ISSN: 1752-8917 (online)		World Academic Press, World Academic Unio		
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• A. Pownuk, Mathematical aspects of grading student's homework in on-line web applications, Journal of Uncertain Systems, 5(2), 141-153, 2011.

Education Mathematics Engineering Generalizations Conclusions

AMPL (A Mathematical Programming Language) is an algebraic modeling language to describe and solve high-complexity problems for large-scale mathematical computing.

```
#VARIABLE DEFINITIONS
var x_1;
var x_2;
#OBJECTIVE FUNCTION (maximize or minimize)
maximize value: x_1 + 2*x_2;
#CONSTRAINTS
subject to condition_1: x_1 + 3*x_2 <= 20;
subject to condition_2: 3*x_1 + x_2 <= 20;
subject to condition_3: x_1 >= 0;
subject to condition_4: x_2 >= 0;
```

Education Mathematics Engineering Generalizations

The optimization problems stored in the work nodes, which are passed to the various inference engines, are kept as directed acyclic graphs (DAG), as well. This representation has big advantages. Hereby, a complete optimization problem is always represented by a single DAG. The vertices of the graph represent operators similar to computational trees. Constants and variables are sources, objective and constraints are sinks of the DAG.

https://www.mat.univie.ac.at/~neum/glopt/coconut/



https://www.mat.univie.ac.at/~neum/glopt/coconut/



Figure: Modeling of engineering problems with uncertainty

A. Neumaier and A. Pownuk, Linear Systems with Large Uncertainties, with Applications to Truss Structures, Journal of Reliable Computing, 13(2), 149-172, 2007.

SAGA - Scientific Computing with Algebraic and Generative Abstractions

Education

Mathematics Engineering Generalizations Conclusions

Algebraic software methodologies are a result of the last 20-30 years investigation into abstract data types and algebraic development techniques. The algebraic concepts also abstract modern program structuring mechanisms like classes and generic (or template) modules of object-oriented programming languages such as C++, Generic Java and Fortran-2000.



https://www.ii.uib.no/saga/

SAGA - Scientific Computing with Algebraic and Generative Abstractions

Education

Mathematics Engineering Generalization

- **Sapphire**: For the quick prototyping of mathematical models an **algebraic programming language** and a compiler that translates recursive functions into non-recursive, imperative code was developed. This allows us to code the recursive equations of the mathematical formulation of a solver directly as recursive functions and compile this for both sequential and parallel HPC computers.
- **Sophus**: This is a software library written in C++ and carefully designed to mimic the abstract structure of the PDE mathematics.
- **CodeBoost**: This is a software transformation system being developed to address the gap between well formed code (from a software engineering point of view) and efficient code (from a run-time point of view).

Fuzzy/Interval Calculator

Education	
Mathematics	
Engineering	Insert a description of interval and fuzzy expressions and press "Calculate" button. [USER'S MANUAL] [{ [0, 6, 14] [0.25, 6.25, 13.5] [0.5, 6.5, 13] [
Generalizations	0.75, 6.75, 12.5) (1, 7, 12) Calculate: The result is:
Conclusions	1/2 ((0,1/51) (1.2,3)) + (1.2)*2
	The program evaluate the value of expressions which contain floating-point, interval and foury mumbers. 1/2*(2*5) Toking-point expression. 1/2*(15,1) Thetval numbers are defined using upper (Deast) and lower (Dain) bounds e.g. (Dain, Xeas]. By default the * operator is assumed between the lines. These too lines are equivalent to the expression 1*2 * (1.2)*(2.3). ([0,1,5], [1,2,3]) Turry number is a collection of alpha-cuts. Each alpha-cut is a trigit alpha, dain, Xaak, Interval and furry numbers. It is possible to add an operator between the inse. 1/2 ([1,2]*(2,3)] These two lines are equivalent to the expression 1*2 * (1.2)*(2.3). The final result is a value of the expression which is created from all the data into data file.

http://www.math.utep.edu/Faculty/ampownuk/php/ fuzzy_calculator/

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Interval Arithmetic

Education Mathematics Engineering Generalizations

An binary operation \star on two intervals, such as addition or multiplication, is defined by

$$[x_1, x_2] \star [y_1, y_2] = \{x \star y \mid x \in [x_1, x_2] \land y \in [y_1, y_2]\}$$

- Interval addition $[x_1, x_2] + [y_1, y_2] = [x_1 + y_1, x_2 + y_2]$
- Interval multiplication $\begin{bmatrix} x_1, x_2 \end{bmatrix} \star \begin{bmatrix} y_1, y_2 \end{bmatrix} = \begin{bmatrix} z_1, z_2 \end{bmatrix}$ where $z_1 = \min\{x_1 \star y_1, x_1 \star y_2, x_2 \star y_1, x_2 \star y_2\},$ $z_2 = \max\{x_1 \star y_1, x_1 \star y_2, x_2 \star y_1, x_2 \star y_2\}.$
- Interval division

$$\frac{[x_1, x_2]}{[y_1, y_2]} = [x_1, x_2] \cdot \frac{1}{[y_1, y_2]}$$

Fuzzy/Interval Calculator

DSL with a description of the mathematical expression Example: [1,2]+2*[3,5]

Code analysis and evaluation

DSL which represents the results Example: [7,12]

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DSL - Domain Specific Language

Fuzzy/Interval Calculator

Education

Mathematics Engineering Generalization

Conclusions

DSL for description of fuzzy and interval numbers.

Input:

```
1+2*([0,1]+1)
{[0,1,5], [1,2,3]} + [1,2]*2
```

Output:

```
{ [ 0, 6, 14 ] [ 0.25, 6.25, 13.5 ]
[ 0.5, 6.5, 13 ] [ 0.75, 6.75, 12.5 ]
[ 1, 7, 12 ] }
```

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Fuzzy Random Variables



Mathematics

Engineering

Generalizations

Conclusions





Differential Equations with Uncertain Parameters



Figure: Second order differential equation

Differential Equations with Uncertain Parameters

Education

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Engineering

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Conclusions

C 🛞 🕲 http://andrzej.pownuk.com/silverlig	ht/VibrationsWithântervalPar	ameters/VibrationsWit	üntervalParameters.html		(5 2 - Q	
VibrationsWithIntervalPara ×						
E= 20059 dE=	5 %	min E = 19000000	0000 max 8	E = 21000000000	rho0 =	[kg/m^3]
A= 0.01 dA =	5 %	min A = 0.0095	max A	A = 0.0105	drho = S	N
3 = 0.3338-6 d3 =	s %	min 3 = 7.916358	06 max 3	3 = 8.74955E-06	min rho= 7480.3	
dt= 0.001 [6]		P = 1000	[N] Time	steps for load = 1	max rho= 8267.7	
L = 10.0 [m]	n- 1		Total	time when the load was applied =	0.001 [s]	
	Ln= 5	[m]				
Init calculations Number of	of interval parameters: 8			P		
List of nodes Number of	of timesteps - 600			· [.	-1	
node 1, x = 0 node 2, x = 5 node 3, x = 10	 Number of DOF = 9 	,	<u></u>	+ <u>_</u>		
			!	L	+	
number of elements = 2	Dof in nodes		Nodes in elements	DOF in eleme	ents	
	0 1 2	-	element 0 0 1	element 0 0 1 2		
Number of nodes = 3	node 1 3 4 5 node 2 6 7 8		element 1 1 2	3 4 5 element 1 3 4 5 6 7 8		

Figure: Input parameters

Online Learning (Numerical Analysis, 1998)





Figure: Web application for teaching of the fininte element method. Description of the problem was given in some DSL.



Lagrangian Mechanics



$$\frac{\mathrm{d}}{\mathrm{d}t} \left(\frac{\partial L}{\partial \dot{q}_j} \right) = \frac{\partial L}{\partial q_j}$$

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Computer methods for finding analytical formulation of the equations of motion in multibody dynamics.

Mathematics Engineering Generalization:



Computer algebra software (Mathematica, Derive, etc.) for numerical methods in the theory of plates.

$$\frac{2Eh^3}{3(1-\nu)}\left(\frac{\partial^4 w}{\partial x_1^4} + 2\frac{\partial^4 w}{\partial x_1^2 \partial x_2^2} + \frac{\partial^4 w}{\partial x_2^4}\right) + q + 2\rho h \frac{\partial^2 u}{\partial t^2} = 0$$

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Education Mathematics Engineering Generalizations

Computer algebra software (Mathematica, Derive, etc.) for numerical methods in the theory of linear elasticity.

$$\frac{1}{2(1-\nu)(1-2\nu)} \left(2(1-\nu)\frac{\partial^2 u_x}{\partial x^2} + \frac{\partial^2 u_y}{\partial x \partial y} + (1-2\nu)\frac{\partial^2 u_x}{\partial y^2} \right) + b_x = 0$$
$$\frac{1}{2(1-\nu)(1-2\nu)} \left(2(1-\nu)\frac{\partial^2 u_y}{\partial y^2} + \frac{\partial^2 u_x}{\partial x \partial y} + (1-2\nu)\frac{\partial^2 u_y}{\partial x^2} \right) + b_y = 0$$

Education Mathematics Engineering Generalizations

- Partial diffrerential equations of elasticity.
- Partial diffrerential equations of plasticity.
- Partial diffrerential equations of viscoelaticity.
- Partial diffrerential equations of the theory of shells and appropriate theory in curvilinear coordinate systems.
- The theory of thin-walled structures.
- Adaptive mesh refinement.
- The theory of variational equations related to the contact mechanics.
- The theory of crack mechanics (fracture mechanics).
- The theory of heat transfer and multiphysics problems.
- etc.

Calculation of the Interval risk by Using Petri Networks and interval Probability



Conclusions



Figure: DSL for description of the engineering problem

M. Betkowski and A. Pownuk, Calculating risk of cost using Monte Carlo simulation with fuzzy parameters in civil engineering, Proceeding of the NSF Workshop on Reliable Engineering Computing, Savannah, Georgia, USA, 179-192, September 15-17, 2004.

Mathematics Engineering

Concranzation

Conclusions

Description of the problem:

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/PREP7	
ET. 1. LINK1	
DI, I, DINKI	
N. 1. 0. 0	
N. 2. 1. 0	
N 3 2 0	
N. 4. 3. 0	
N 5 0 1	
N. 6. 1. 1	
N 7 2 1	
N. 8. 3. 1	
N 9 0 2	
N. 10. 1. 2	
N 11 2 2	
N. 12. 3. 2	
.,, ., .	
MP, EX, 1, 2.1e+11	
R. 1. 0.0025	
MAT 1	
REAL 1	
Description of interval param	eters (hel

MP, EX, 1, 5 R, 1, 5

Sensitivity analysis method
 Calculate

http://www.math.utep.edu/Faculty/ampownuk/php/ ansys2interval/ansys-code.php

Education

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Conclusions

Time of calculation: 0.004996 [s Number of DOF: 16 Number of elements: 26 Number of nodes: 12	sec]				^
u[0]= [2.54206368927894e-05,	2.70758977991233e-05,	2.88890319829459e-05]	node=	5 dof= 1	
u[1]= [-2.416132318422010-06, u[2]= [1.89488493026688e-05,	-1.45525064589709e-06, 2.03244670585942e-05,	2.18240888299457e-05]	node=	6 dof= 2 6 dof= 1	
u[3]= [-1.18336781275183e-05, u[4]= [1.74375666485017e-05,	-1.07203077121679e-05, 1.86853353510165e-05,	-9.68801242678198e-06] 2.00368684309889e-051	node= node=	5 dof= 2 7 dof= 1	
u[5]= [-1.53016570105788e-05,	-1.40293414211092e-05,	-1.28438219917361e-05]	node=	7 dof= 2	
u[7]= [-2.43184098360924e-05,	-2.27501214588593e-05,	-2.13175562611172e-05]	node= 1	3 dof= 1 3 dof= 2	
u[8]= [4.47984203980532e-05, u[9]= [-1.25873042500698e-05.	4.76520021045755e-05, -1.0800778851294e-05.	5.07482294189415e-05] -9.13828295995457e-061	node=	9 dof= 1 9 dof= 2	
u[10]= [3.58319463043394e-05,	3.83064738991786e-05,	4.09641151999668e-05]	node= 1	0 dof= 1	
u[11]= [-2.03184368590144e-05, u[12]= [3.30408793908687e-05,	-1.88999001199072e-05, 3.54230615860712e-05,	3.79901925037356e-05]	node= 10 node= 10	1 dof= 2	
u[13] = [-2.87524495626644e-05, u[14] = [-3.51831538994549e-05]	-2.70377395621771e-05, 3.77051247175134e-05	-2.54594638852595e-05]	node= 1	l dof= 2	
$11[15] = [-4 \ 18322390326742e-05]$	-3 95037800489603e-05.	-3.7394527683613e-051	node= 1	2 dof = 2	×

http://www.math.utep.edu/Faculty/ampownuk/php/ ansys2interval/ansys-code.php

Education

Mathematic

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Conclusions

ANSYS Parametric Design Language (APDL)

MP, EX, 1, 2.1e+11 R, 1, 0.0025 MAT 1 REAL 1

Extension of the ANSYS Parametric Design Language (APDL) which describes uncertainty of parameters.

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MP, EX, 1, 5
R, 1, 5
```

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Interval Finite Element Method for the 2D Linear Elasticity Problems





Figure: Solution of system of partial differential equations







A. Pownuk, Numerical solutions of fuzzy partial differential equation and its application in computational mechanics, In:
M. Nikravesh, L. Zadeh and V. Korotkikh, (eds.), Fuzzy Partial Differential Equations and Relational Equations: Reservoir Characterization and Modeling, 308-347, Springer 2004.

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Summary of My Research on Modeling of Uncertainty



Conclusions



A. Pownuk and V. Kreinovich, Combining Interval, Probabilistic, and Other Types of Uncertainty in Engineering Applications, Springer 2018.

Chevron Oil Company



Figure: Research for Chevron Oil Comapny

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Commercial FEM Software for Designing Truss and Frame Structures

Mathematic

Engineering

- Generalizations
- Conclusions



FEM Equations form APDL





Figure: Sample engineering structure

http://www.math.utep.edu/Faculty/ampownuk/php/ fem-equations/fem-equations.php

FEM Equations form APDL



Generate Equations
 Calculate

Figure: APDL description of engineering problem

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http://www.math.utep.edu/Faculty/ampownuk/php/ fem-equations/fem-equations.php

Engineering

FEM Method

Education Mathematics Engineering Generalizations

$$\frac{d}{dx}\left(EA\frac{du}{dx}\right) + n = 0, u(0) = 0, u(L) = 0$$

$$\int_{0}^{L} \frac{d}{dx}\left(EA\frac{du}{dx}\right)vdx + \int_{0}^{L} nvdx = \int_{0}^{L} 0vdx, u(0) = 0, u(L) = 0$$

$$\int_{0}^{L} \frac{d}{dx}\left(EA\frac{du}{dx}\right)vdx =$$

$$= \int_{0}^{L} EA\frac{du}{dx}\frac{dv}{dx}dx + EA\frac{du(0)}{dx}v(0) - EA\frac{du(L)}{dx}v(L)$$

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Local Stiffness Matrix



1D Truss Element



1D element

$$\mathcal{K} = \begin{bmatrix} \frac{EA}{L} & -\frac{EA}{L} \\ -\frac{EA}{L} & \frac{EA}{L} \end{bmatrix}$$

2D element

$$\mathcal{K} = \begin{bmatrix} \frac{EA}{L} & 0 & -\frac{EA}{L} & 0\\ 0 & 0 & 0 & 0\\ -\frac{EA}{L} & 0 & \frac{EA}{L} & 0\\ 0 & 0 & 0 & 0 \end{bmatrix}$$

etc.

Global Stiffness Matrix



How to Efficiently use Available Tools?

Education Mathematics Engineering Generalizations

Conclusions



Figure: Tools in the past



Figure: Tools now

Advantages of the Automated Computational Methods

Education Mathematics Engineering Generalizations



Automation of some part of the engineering computational process:

- faster design,
- more optimal products,
- cheaper engineering structures.

Advantages of the Automated Computational Methods



Conclusions



Some part of the the computational algorithms can be automated. There are several benefites of this process:

- calculations are faster,
- it is possible to analysie more results,
- it is possible to solve some problems with high complexity.

Conclusions

- Education Mathematics Engineering Generalizatio
- Conclusions

- Syntax and grammar analysis of the mathematical statements can improve online learning systems.
- Some optimization problems and some aspects of theory of partial differential equations can be can be solved automatically by using special software methodologies.
- Automated development of mathematical models speeds up calculations and and software development.

Education

Conclusions

Thank You